

Parameterized Model Order Reduction of Delayed Systems using an Interpolation Approach with Amplitude and Frequency Scaling Coefficients

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Outline

Introduction

PMOR for delayed systems

Numerical results

Conclusions

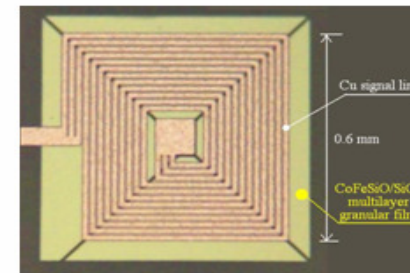
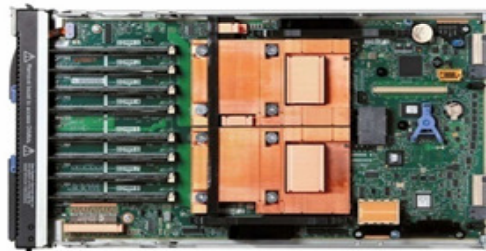
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A typical design process requires



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- **design space optimization**
- **design space exploration**
- **sensitivity analysis**
 - multiple simulations (measurements)
 - different design parameters values (e.g. layout features)



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- **Multiple simulations (measurements)**
 - **computationally expensive (time and memory)**



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- **Multiple simulations (measurements)**
 - **computationally expensive (time and memory)**
- **Can we do better?**



A typical design process requires

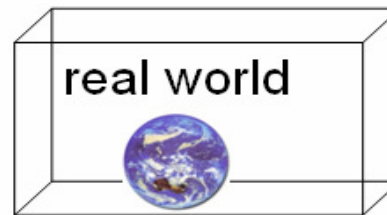
- Multiple simulations (measurements)
 - computationally expensive (time and memory)

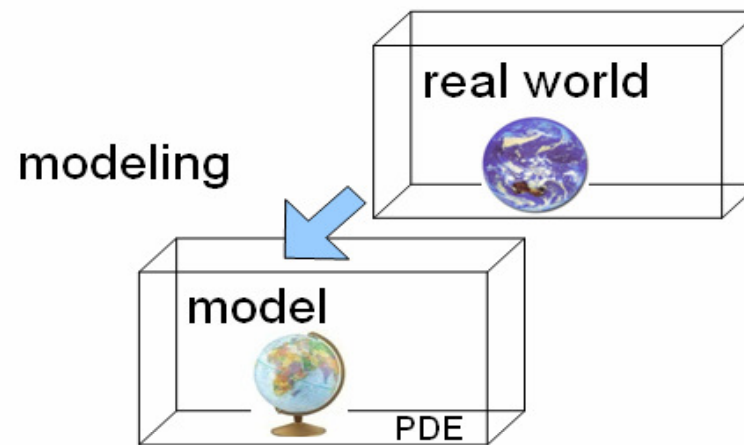


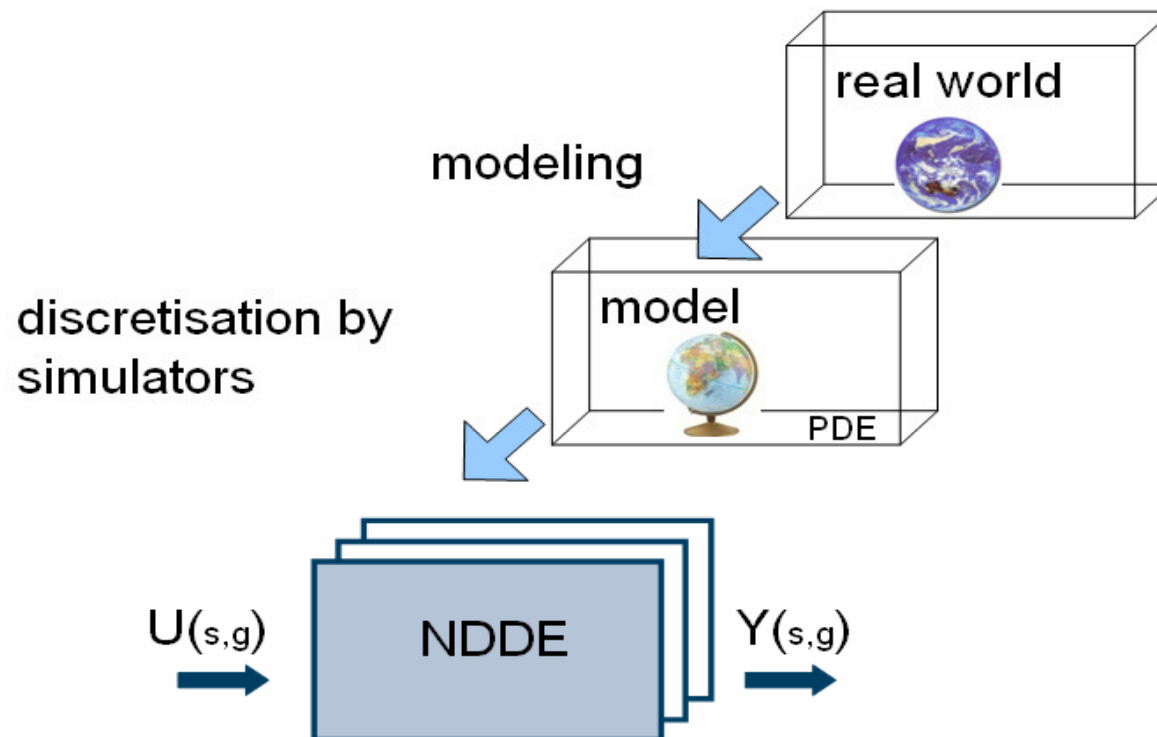
- Can we do better?

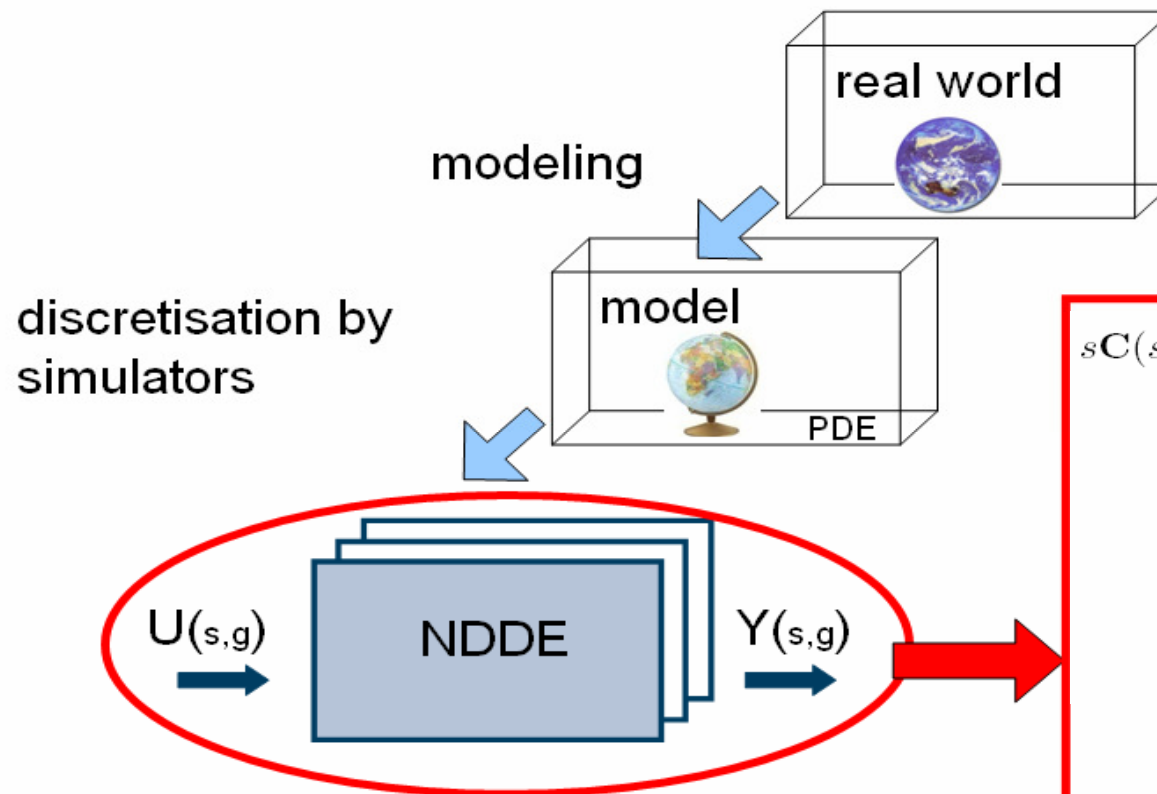
- **Yes**
 - **By parameterized reduced order models**











$$s\mathbf{C}(s, g)\mathbf{X}(s, g) = -\mathbf{G}(s, g)\mathbf{X}(s, g) + \mathbf{B}\mathbf{U}(s)$$

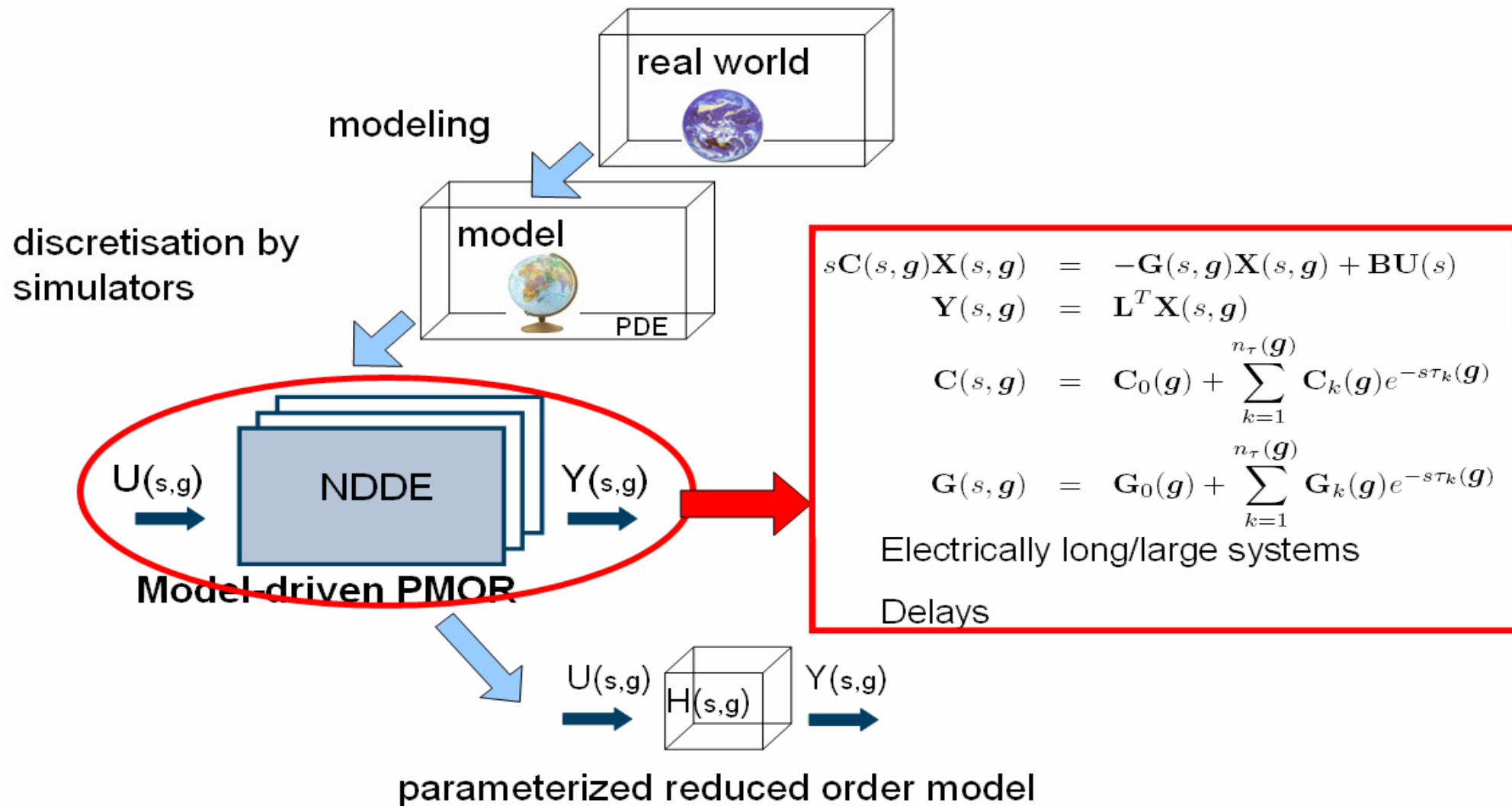
$$\mathbf{Y}(s, g) = \mathbf{L}^T \mathbf{X}(s, g)$$

$$\mathbf{C}(s, g) = \mathbf{C}_0(g) + \sum_{k=1}^{n_\tau(g)} \mathbf{C}_k(g)e^{-s\tau_k(g)}$$

$$\mathbf{G}(s, g) = \mathbf{G}_0(g) + \sum_{k=1}^{n_\tau(g)} \mathbf{G}_k(g)e^{-s\tau_k(g)}$$

Electrically long/large systems

Delays



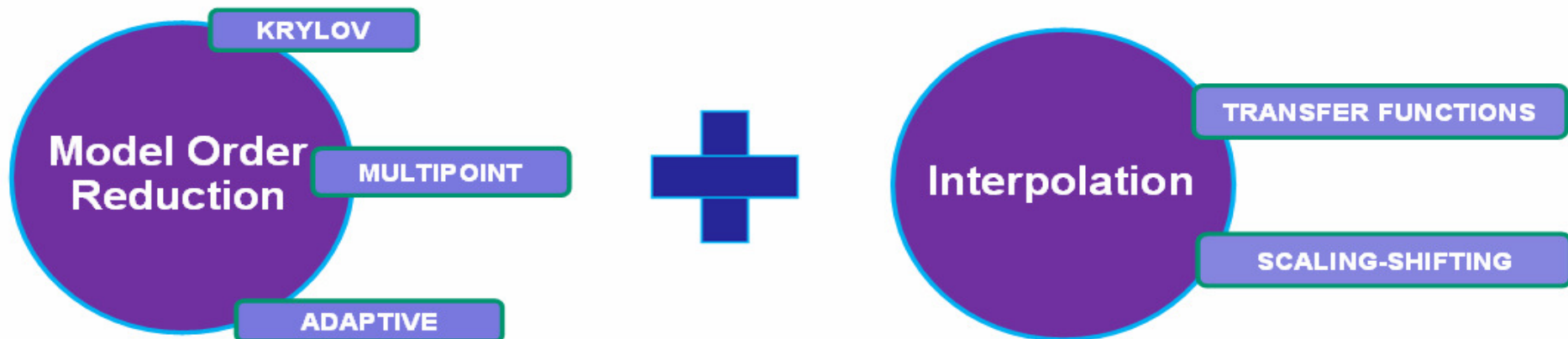
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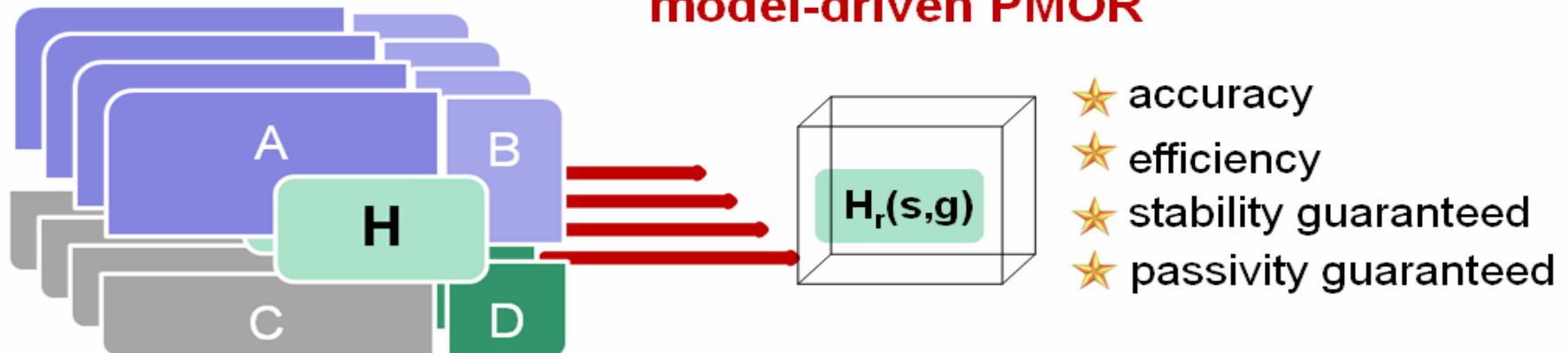
PMOR for delayed systems

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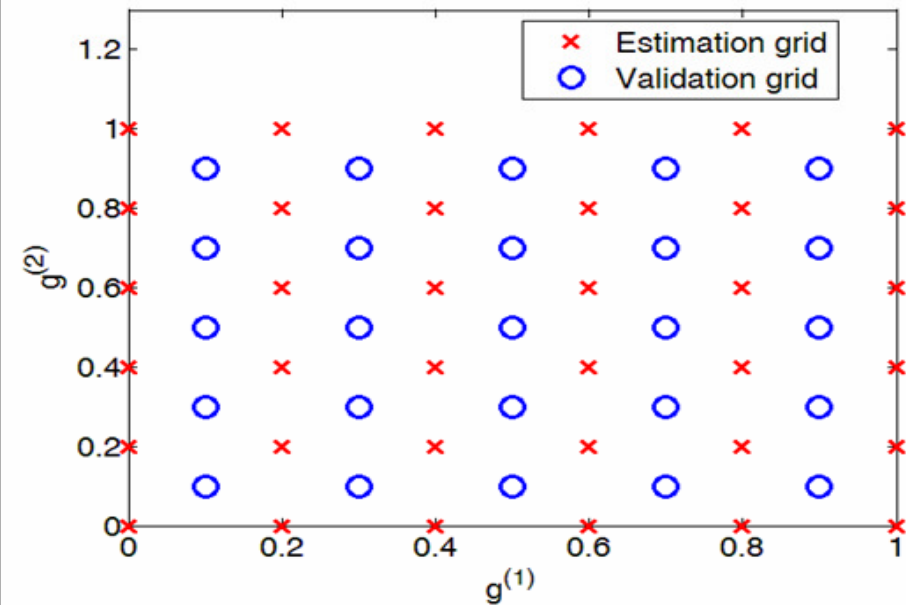
Conclusions



model-driven PMOR



Design space $\mathbf{g} = (g^{(n)})_{n=1}^N$



Compute τ ROMs $\mathbf{R}(s, \mathbf{g}_k^{\Omega_i})$
in the estimation design space grid

Compute scaling and frequency shifting coefficients
 $\alpha_{1,k}(\mathbf{g}_j^{\Omega_i}), \alpha_{2,k}(\mathbf{g}_j^{\Omega_i})$
in the estimation design space grid

Multivariate interpolation of
scaling and frequency shifting coefficients
 $\alpha_1(\mathbf{g}), \alpha_2(\mathbf{g})$

Multivariate interpolation of
scaled and shifted τ ROMs
 $\alpha_1(\mathbf{g})\mathbf{R}(s\alpha_2(\mathbf{g}), \mathbf{g})$

Features

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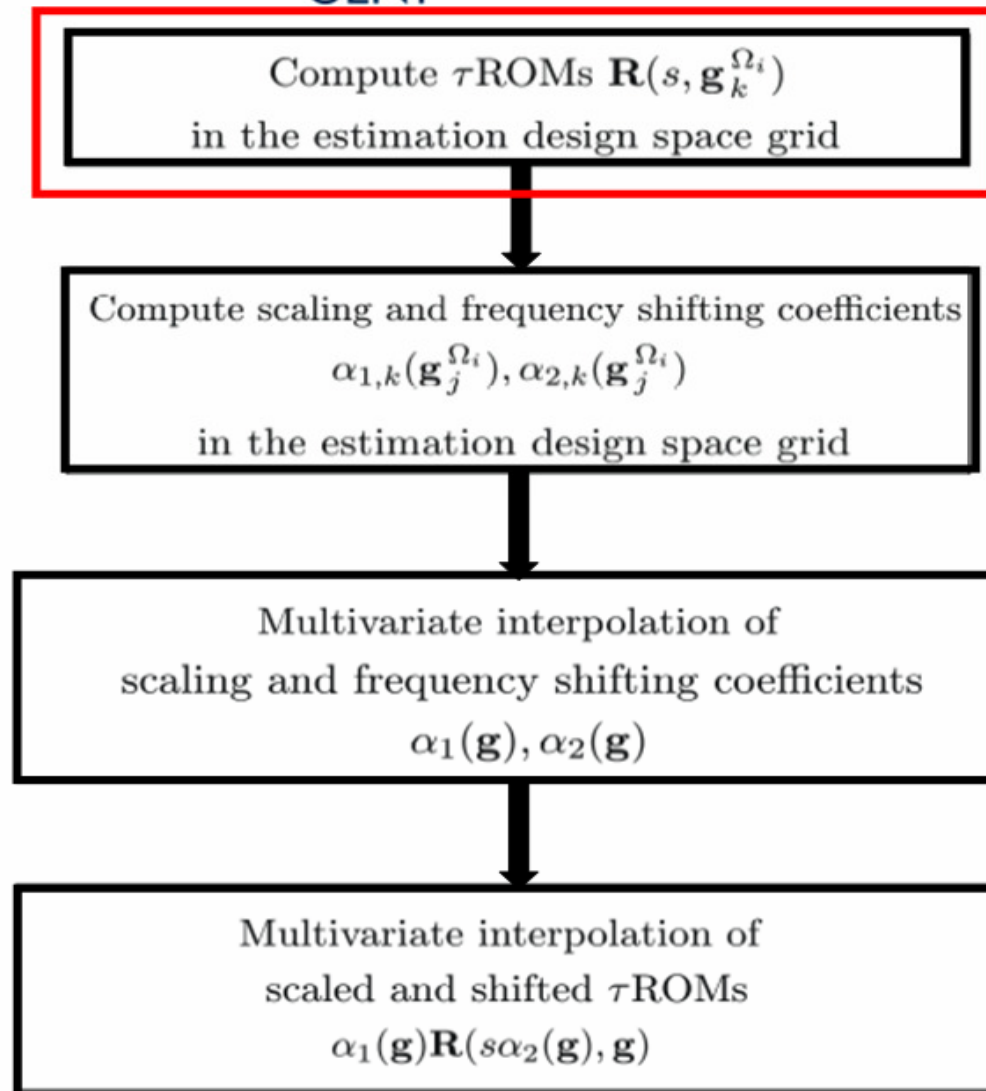
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- **stability and passivity guaranteed over the design space**

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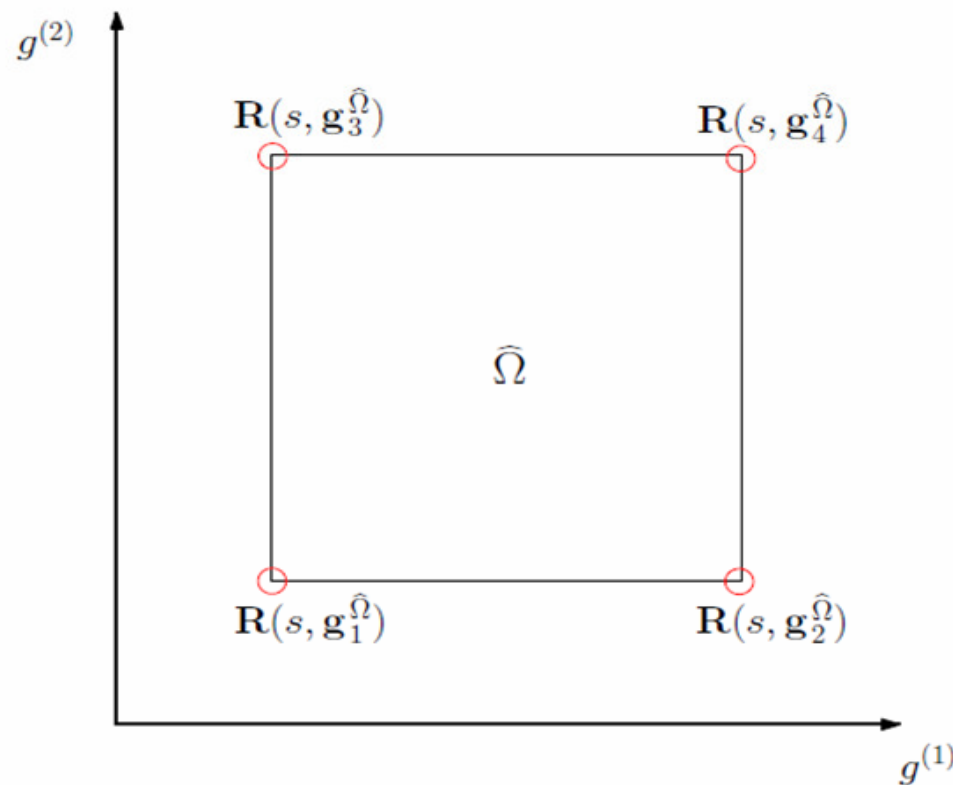
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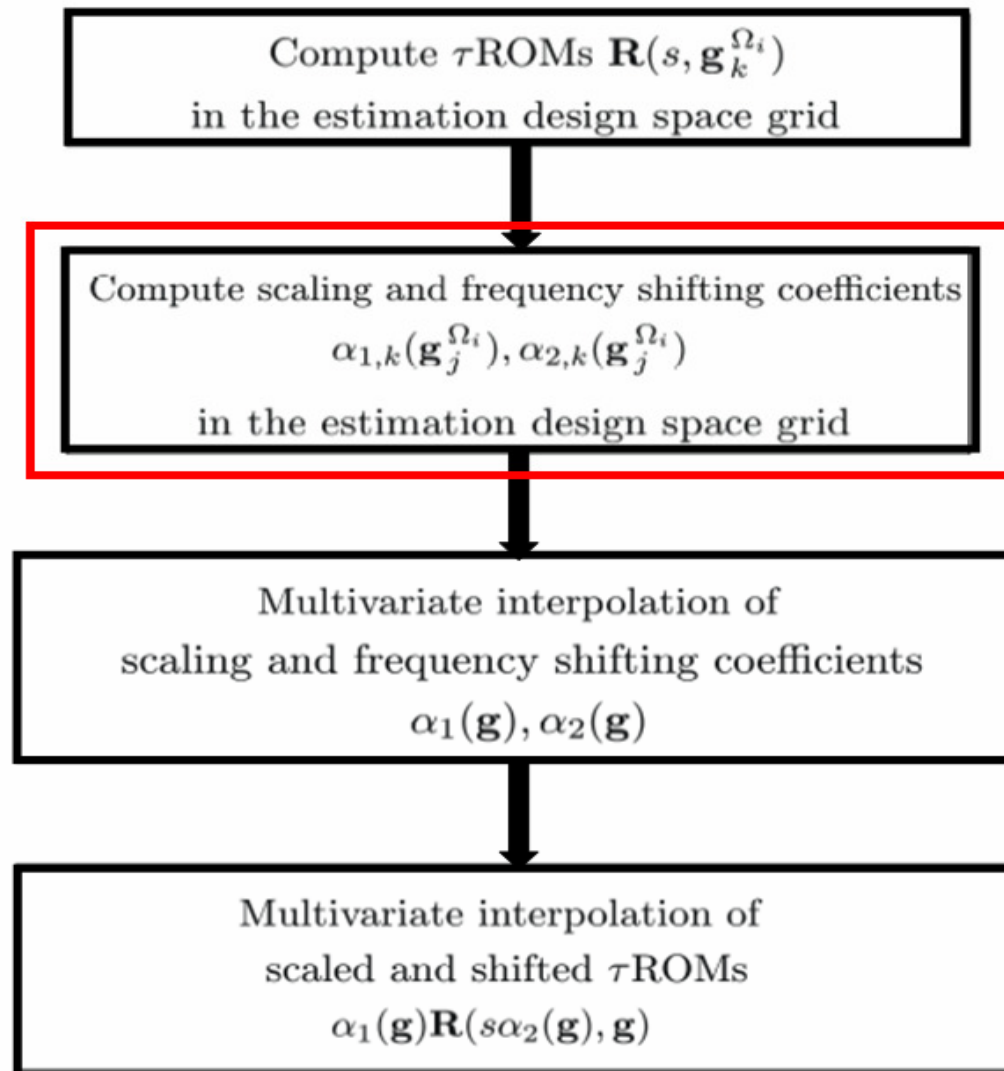
- **each design space cell has its own model**
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- **stability and passivity guaranteed over the design space**
- **suitable to robust adaptive sampling**
- **different flavours**



τ ROMs at the cell vertices

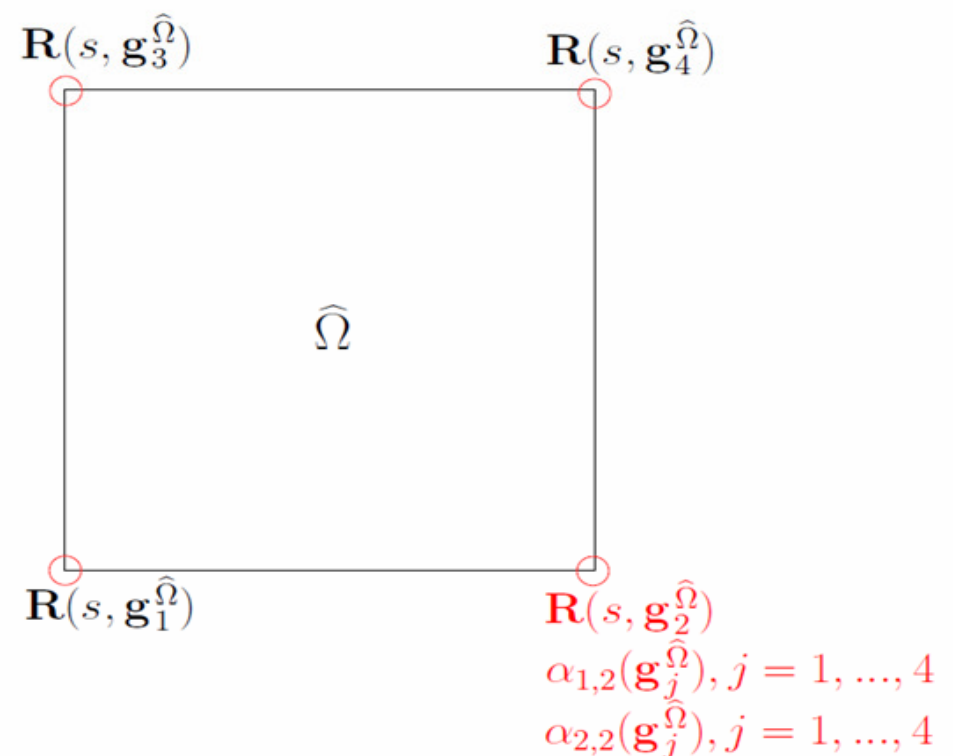
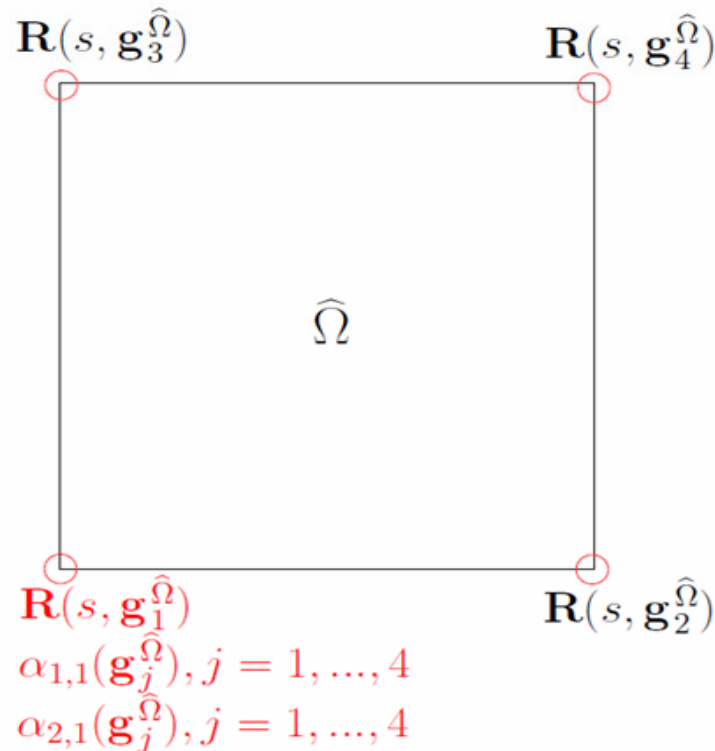


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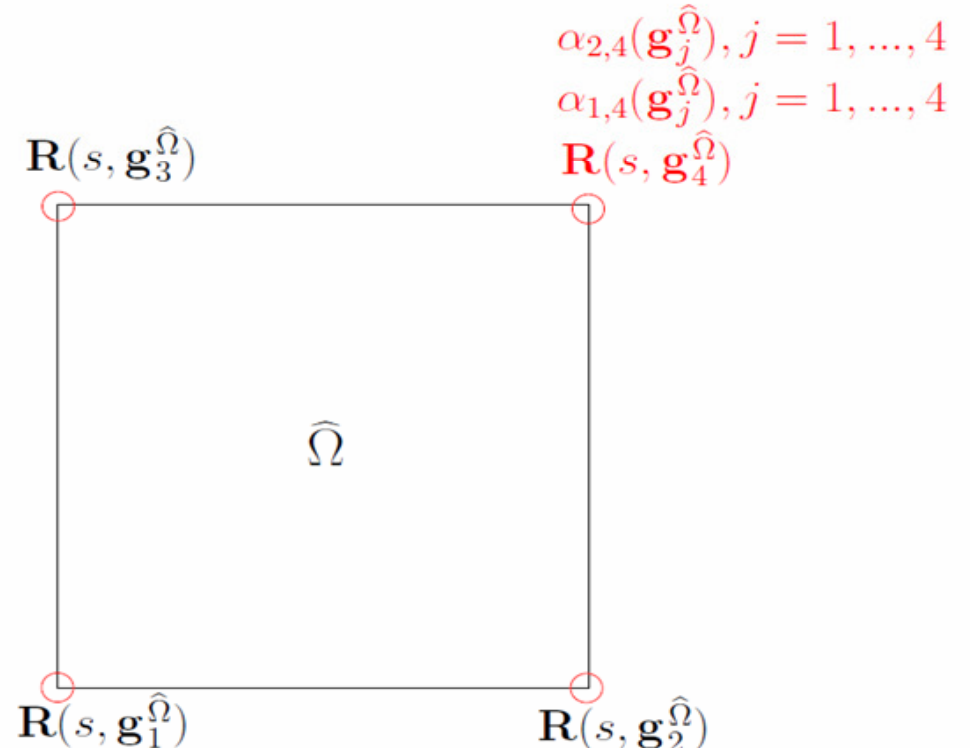
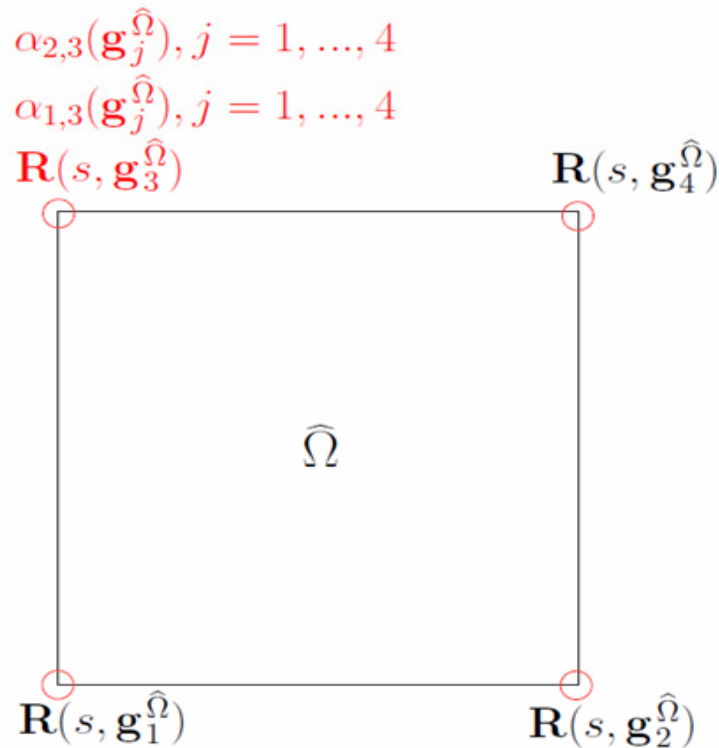
$$\min_{\alpha_{1,k}(\mathbf{g}_j^{\hat{\Omega}}), \alpha_{2,k}(\mathbf{g}_j^{\hat{\Omega}})} \text{Err}(\tilde{\mathbf{R}}(s, \mathbf{g}_k^{\hat{\Omega}}), \mathbf{R}(s, \mathbf{g}_j^{\hat{\Omega}}))$$

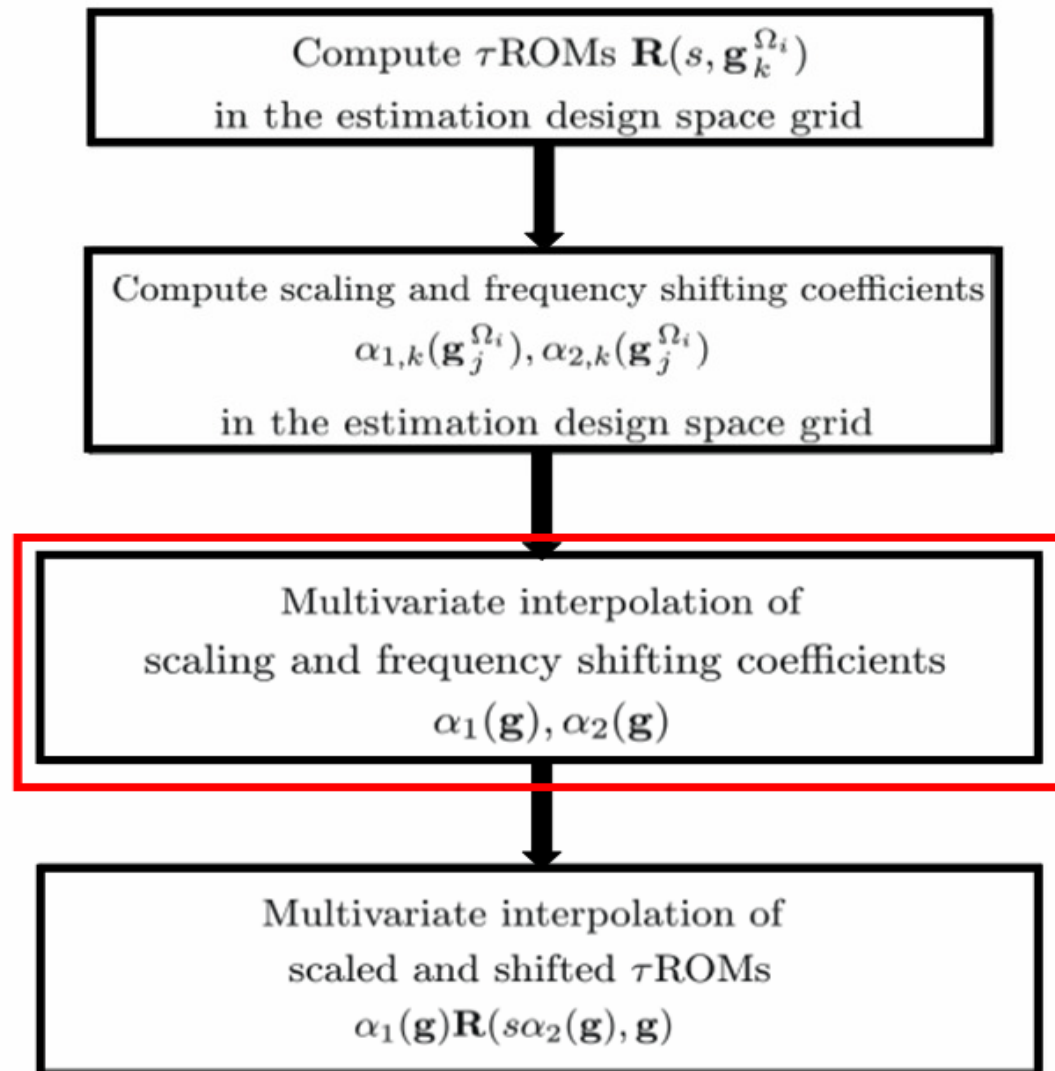
$$\begin{aligned} \tilde{\mathbf{R}}(s, \mathbf{g}_k^{\hat{\Omega}}) &= \alpha_{1,k}(\mathbf{g}_j^{\hat{\Omega}}) \mathbf{R}(s, \alpha_{2,k}(\mathbf{g}_j^{\hat{\Omega}}), \mathbf{g}_k^{\hat{\Omega}}) \\ \alpha_{1,k}(\mathbf{g}_j^{\hat{\Omega}}) &= \alpha_{2,k}(\mathbf{g}_j^{\hat{\Omega}}) = 1, \quad j = k \end{aligned}$$

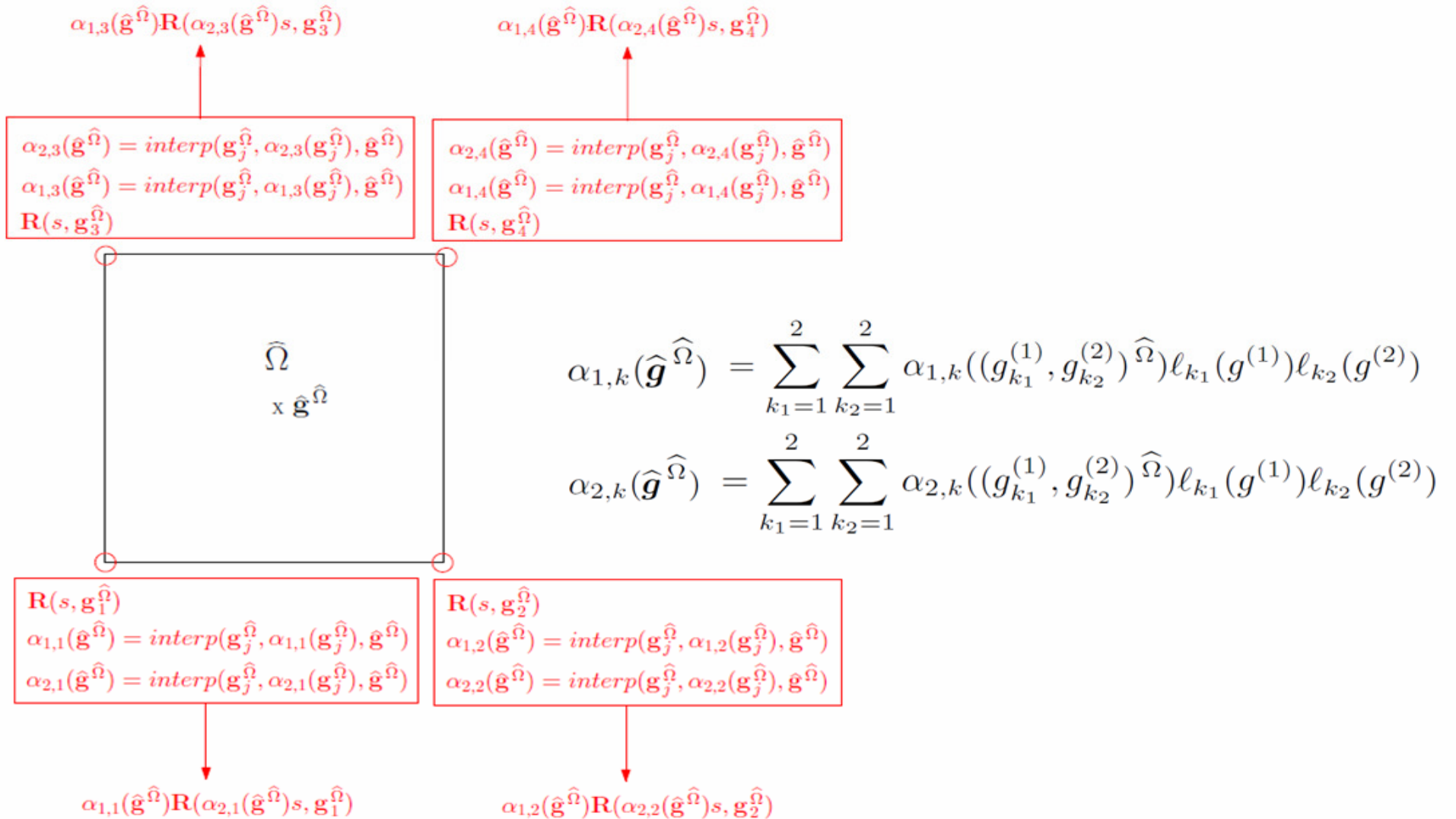


$$\min_{\alpha_{1,k}(\mathbf{g}_j^{\hat{\Omega}}), \alpha_{2,k}(\mathbf{g}_j^{\hat{\Omega}})} \text{Err}(\tilde{\mathbf{R}}(s, \mathbf{g}_k^{\hat{\Omega}}), \mathbf{R}(s, \mathbf{g}_j^{\hat{\Omega}}))$$

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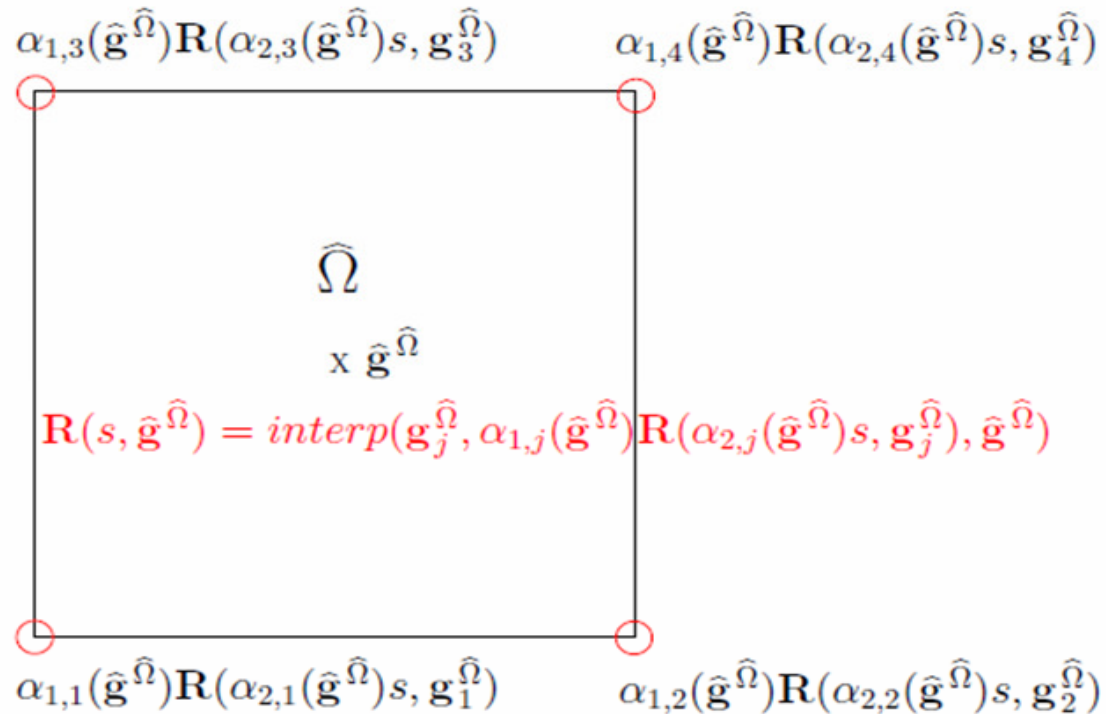


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$$\mathbf{R}(s, \hat{\mathbf{g}}^{\hat{\Omega}}) = \text{interp}(\mathbf{g}_j^{\hat{\Omega}}, \alpha_{1,j}(\hat{\mathbf{g}}^{\hat{\Omega}})\mathbf{R}(\alpha_{2,j}(\hat{\mathbf{g}}^{\hat{\Omega}})s, \mathbf{g}_j^{\hat{\Omega}}), \hat{\mathbf{g}}^{\hat{\Omega}})$$

$$\mathbf{R}(s, \hat{\mathbf{g}}^{\hat{\Omega}}) = \sum_{k_1=1}^2 \sum_{k_2=1}^2 \tilde{\mathbf{R}}(s, (g_{k_1}^{(1)}, g_{k_2}^{(2)})^{\hat{\Omega}}) \ell_{k_1}(g^{(1)}) \ell_{k_2}(g^{(2)})$$

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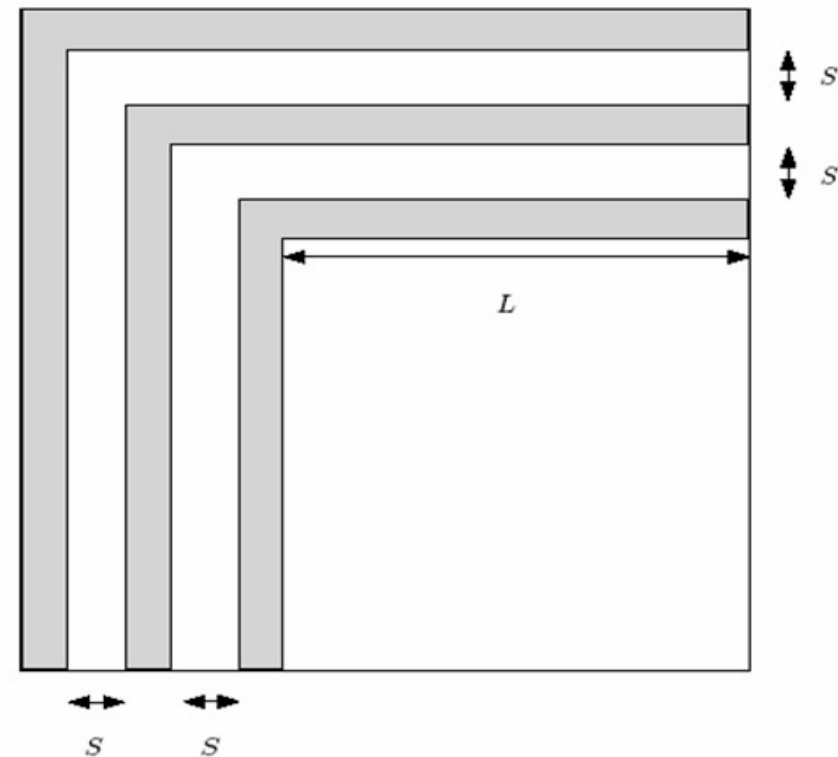
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3D example: Bends

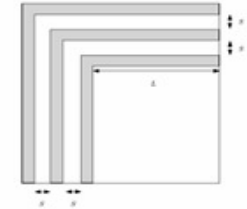
Parameter	Min	Max
Frequency (<i>freq</i>)	100 kHz	10 GHz
Length (<i>L</i>)	1 cm	1.3 cm
Spacing (<i>S</i>)	2.5 mm	3 mm

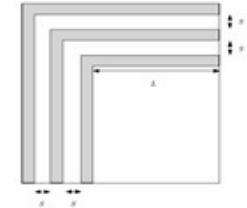
Estimation grid by solver (6×5) (L,S)
Validation grid by solver (5×4) (L,S)



(ORDER, DELAYS) OF τ PEEC MODELS AND τ ROMs.

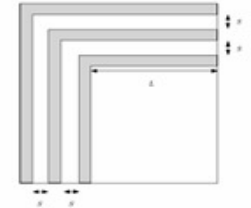
	τ PEEC models	τ ROMs
(L_1, S_1)	(2124,510)	(64,510)
(L_2, S_1)	(2124,508)	(64,508)
(L_3, S_1)	(2124,510)	(64,510)
(L_4, S_1)	(2124,511)	(64,511)
(L_5, S_1)	(2124,517)	(64,517)
(L_6, S_1)	(2124,519)	(64,519)
(L_1, S_2)	(2124,509)	(64,509)
(L_2, S_2)	(2124,511)	(64,511)
(L_3, S_2)	(2124,513)	(64,513)
(L_4, S_2)	(2124,512)	(64,512)
(L_5, S_2)	(2124,519)	(64,519)
(L_6, S_2)	(2124,520)	(80,520)
(L_1, S_3)	(2124,511)	(64,511)
(L_2, S_3)	(2124,514)	(64,514)
(L_3, S_3)	(2124,518)	(64,518)
(L_4, S_3)	(2124,515)	(64,515)
(L_5, S_3)	(2124,518)	(64,518)
(L_6, S_3)	(2124,522)	(64,522)
(L_1, S_4)	(2124,511)	(64,511)
(L_2, S_4)	(2124,512)	(64,512)
(L_3, S_4)	(2124,519)	(64,519)
(L_4, S_4)	(2124,519)	(64,519)
(L_5, S_4)	(2124,519)	(64,519)
(L_6, S_4)	(2124,527)	(64,527)
(L_1, S_5)	(2124,510)	(64,510)
(L_2, S_5)	(2124,513)	(64,513)
(L_3, S_5)	(2124,518)	(64,518)
(L_4, S_5)	(2124,520)	(64,520)
(L_5, S_5)	(2124,519)	(80,519)
(L_6, S_5)	(2124,524)	(64,524)





Original order	2124
Reduced order	64-272

Step	CPU time
Evaluating solver (one frequency response - 1 sample)	15 s
Evaluating model (one frequency response - 1 sample)	0.24 s

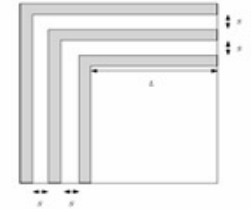


Original order	2124
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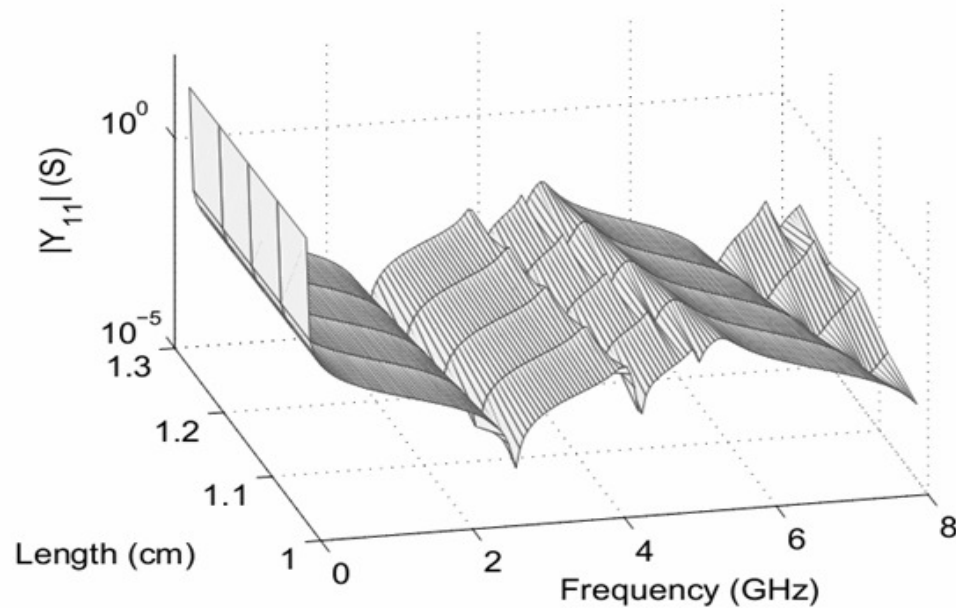
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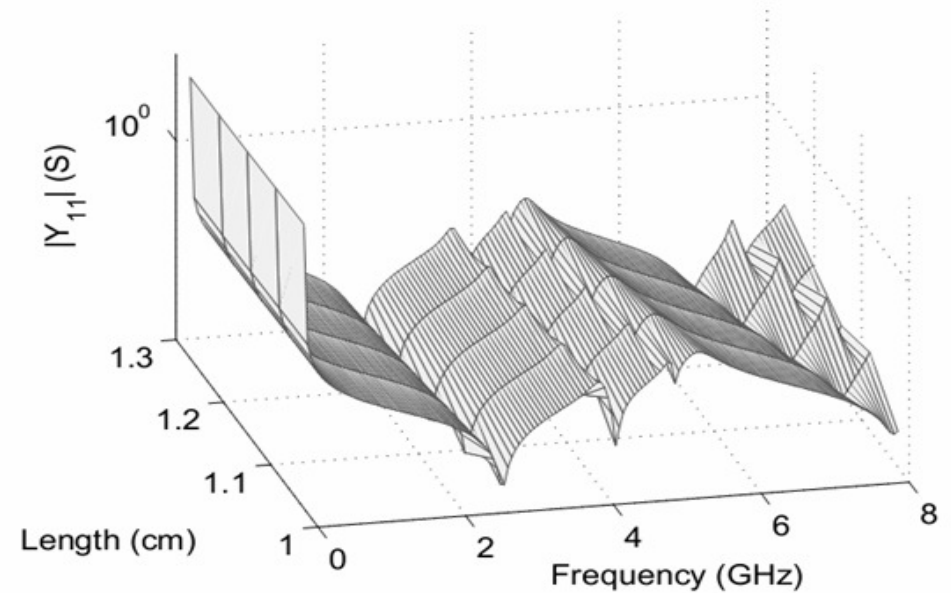
Speed-up 62.5 x

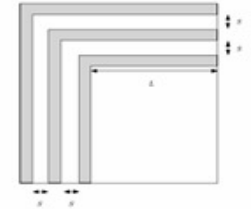


$S=2.56$ mm

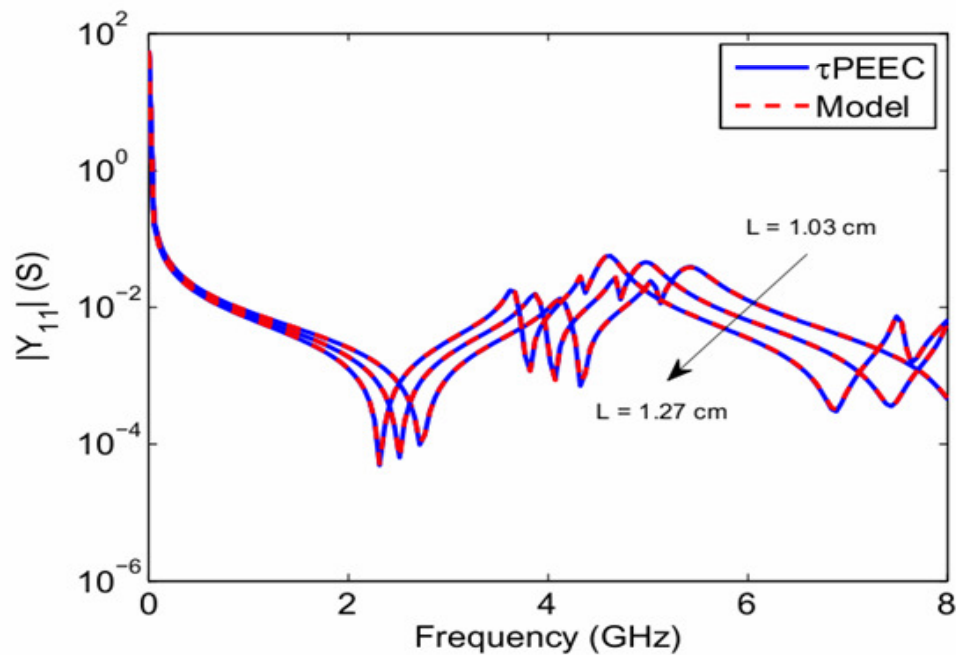


$S=2.94$ mm

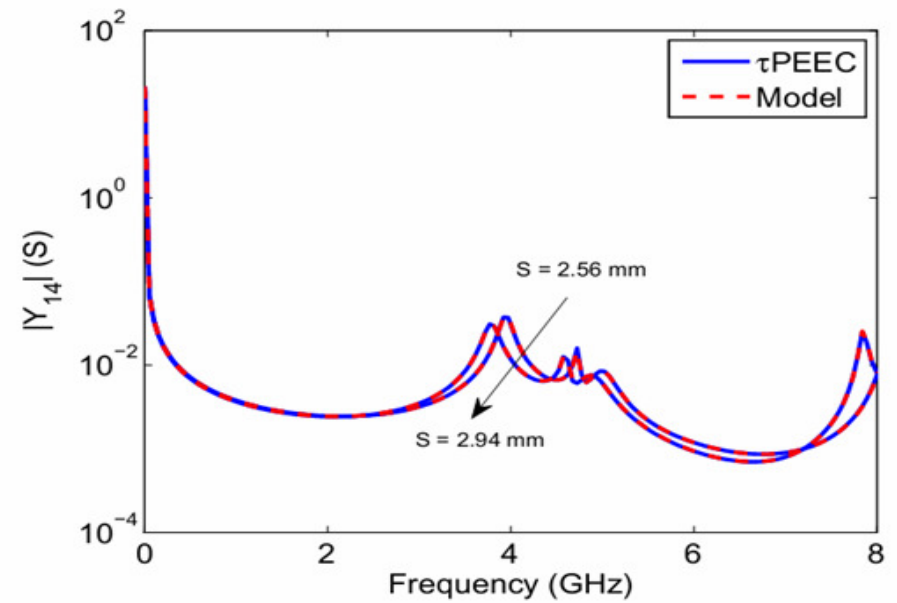




$S=2.69$ mm



$L=1.15$ mm



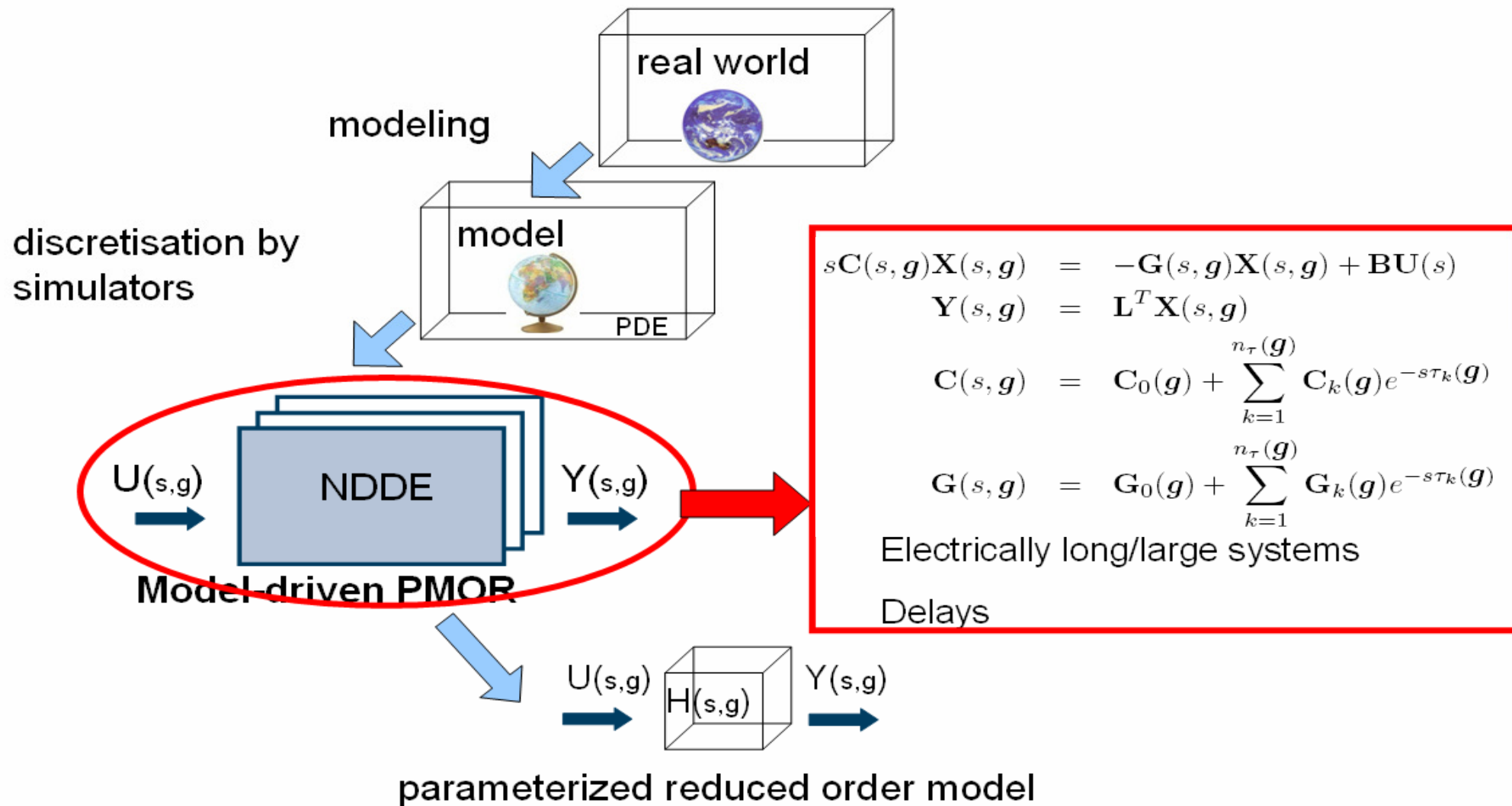
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Questions



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Recent publications

- F. Ferranti, M. Nakhla, G. Antonini, T. Dhaene, L. Knockaert, A. Ruehli, "Multipoint Full-Wave Model Order Reduction for Delayed PEEC Models with Large Delays", IEEE Transactions on Electromagnetic Compatibility, vol. 53, no. 4, pp. 959-967, November 2011
- F. Ferranti, M. Nakhla, G. Antonini, T. Dhaene, L. Knockaert, A. E. Ruehli, "Interpolation-based Parameterized Model Order Reduction of Delayed Systems", IEEE Trans. on Microwave Theory and Techniques, vol. 60, no. 3, pp. 431-440, March 2012.

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