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Method of Moment Solution of SVS-EFIE for 2D Transmission Lines of Complex Cross-Sections

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Outline

- **Integral Equation Approaches for RL extraction**
 - Volume-IE
 - Surface-Volume-Surface IE
- **Method of Moment for SVS-EFIE**
 - Surface and volume meshing
 - Matrix structure
- **Numerical results**
 - Circular conductor: SVS-EFIE vs. Analytic Solution
 - Differential pair: SVS-EFIE vs. Volume-IE
 - Coaxial cable: SVS-EFIE vs. Volume-IE

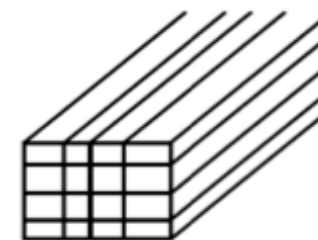


Traditional Volume-EFIE

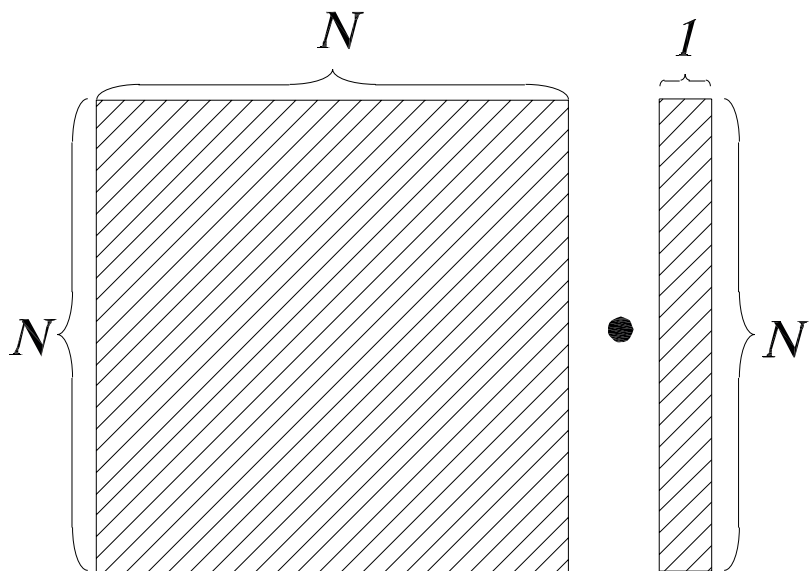
Volume EFIE $\rightarrow \frac{j_z(\vec{\rho})}{\sigma} + i\omega\mu_0 \iint_S \boxed{G_0(\vec{\rho}, \vec{\rho}')} j_z(\vec{\rho}') ds' = -V_{p.u.l.}, \vec{\rho} \in S$

Static Green's function $\rightarrow$

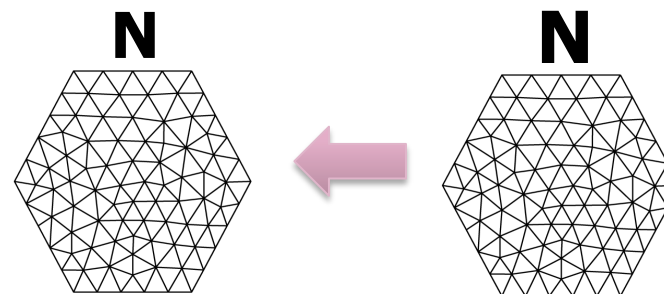
$$\boxed{G_0(\vec{\rho}, \vec{\rho}') = -\frac{1}{2\pi} \ln(|\vec{\rho} - \vec{\rho}'|)}$$



Matrix-vector product:



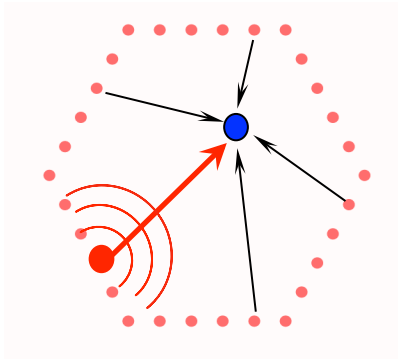
Volumetric mesh:





Surface-Volume-Surface EFIE

Volume EFIE $\rightarrow$ $E_z(\vec{\rho}) + i\omega\mu_0\sigma \iint_S G_0(\vec{\rho}, \vec{\rho}') E_z(\vec{\rho}') ds' = -V_{p.u.l.}, \vec{\rho} \in S$



$$E_z(\vec{\rho}) = -i\omega\mu_0 \int_{\partial S} G_\sigma(\vec{\rho}, \vec{\rho}') J_z(\vec{\rho}') d\vec{\rho}', \quad \vec{\rho} \in S$$

Full-wave Green's function $\rightarrow$ $G_\sigma(\vec{\rho}, \vec{\rho}') = \frac{i}{4} H_0^{(2)}(k_\sigma |\vec{\rho} - \vec{\rho}'|) \quad k_\sigma = \sqrt{\frac{\omega\mu_0\sigma}{2}}(1-i)$

Surface-Volume-Surface EFIE:

$$i\omega\mu_0 \int_{\partial S} G_\sigma(\vec{\rho}, \vec{\rho}') J_z(\vec{\rho}') d\vec{\rho}' + \sigma(\omega\mu_0)^2 \int_{\partial S} \left[\iint_S G_0(\vec{\rho}, \vec{\rho}') G_\sigma(\vec{\rho}', \vec{\rho}'') ds' \right] J_z(\vec{\rho}'') d\vec{\rho}'' = V_{p.u.l.}$$

$$\vec{\rho} \in \partial S.$$



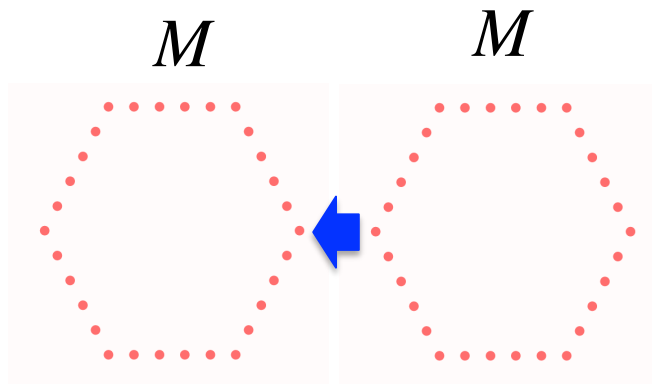
SVS-EFIE: Operators

SVS-EFIE in operator form:

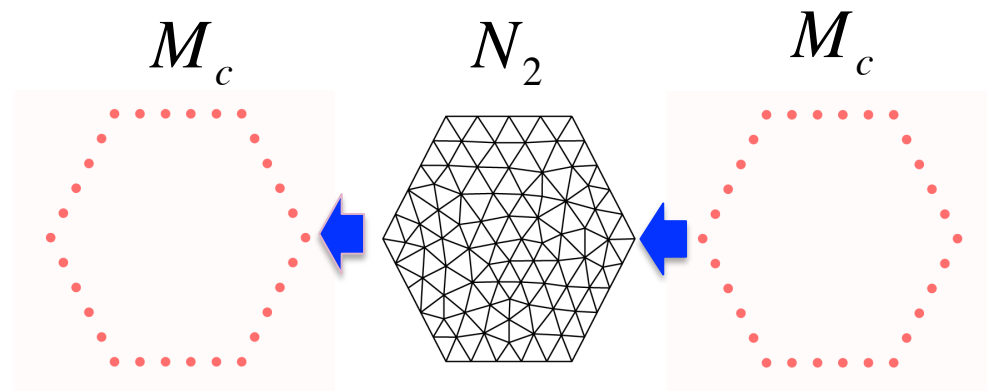
$$T_{\sigma}^{\partial S, \partial S} \circ J_z + \sigma T_0^{\partial S, S} \circ T_{\sigma}^{S, \partial S} \circ J_z = -V_{p.u.l.}$$



Surface-to-Surface mapping
(global impedance operator)



Surface-to-Volume-to-Surface mapping:

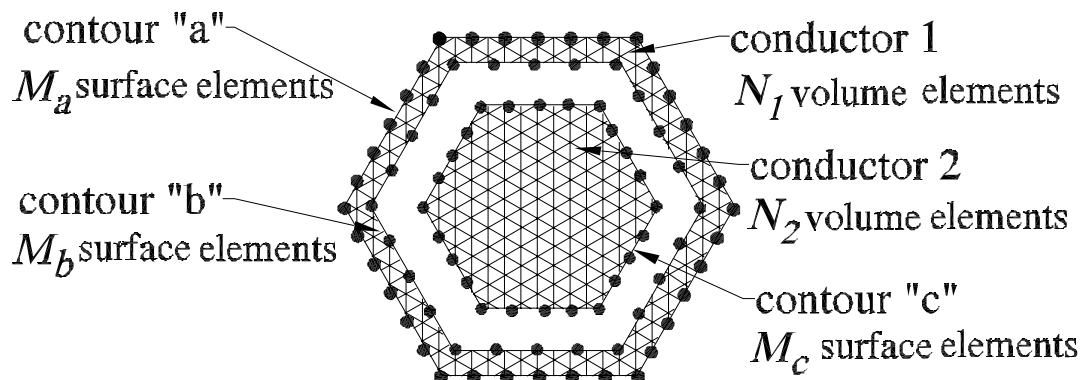


SVS-EFIE in matrix form:

$$(Z_{\sigma}^{\partial S, \partial S} + \sigma Z_0^{\partial S, S} \cdot Z_{\sigma}^{S, \partial S}) \cdot \mathbf{I} = \mathbf{V}$$



SVS-EFIE: Matrix structure



$$\begin{pmatrix} \mathbf{Z}_\sigma^{\partial S, \partial S} \end{pmatrix} + \begin{pmatrix} \sigma \mathbf{Z}_0^{\partial S, S} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{Z}_\sigma^{S, \partial S} \end{pmatrix} \cdot \mathbf{I} = \mathbf{V}$$

$$\begin{matrix}
 \begin{matrix} M_a & M_b \\ \hline \begin{matrix} \mathbf{Z}_\sigma^{\partial S_a, \partial S_a} & \mathbf{Z}_\sigma^{\partial S_a, \partial S_b} \\ \mathbf{Z}_\sigma^{\partial S_b, \partial S_a} & \mathbf{Z}_\sigma^{\partial S_b, \partial S_b} \end{matrix} & 0 \\ \hline 0 & \mathbf{Z}_\sigma^{\partial S_c, \partial S_b} \end{matrix} & + & \begin{matrix} N_1 & N_2 \\ \hline \begin{matrix} \mathbf{Z}_0^{\partial S_a, S_1} & \mathbf{Z}_0^{\partial S_a, S_2} \\ \mathbf{Z}_0^{\partial S_b, S_1} & \mathbf{Z}_0^{\partial S_b, S_2} \\ \mathbf{Z}_0^{\partial S_c, S_1} & \mathbf{Z}_0^{\partial S_c, S_2} \end{matrix} \\ \hline \end{matrix} & \cdot & \begin{matrix} M_a & M_b \\ \hline \begin{matrix} \mathbf{Z}_\sigma^{S_1, \partial S_a} & \mathbf{Z}_\sigma^{S_1, \partial S_b} \\ 0 & \mathbf{Z}_\sigma^{S_2, \partial S_c} \end{matrix} \\ \hline 0 & \mathbf{Z}_\sigma^{S_2, \partial S_c} \end{matrix}
 \end{matrix} \cdot \begin{matrix} \mathbf{I}^a \\ \mathbf{I}^b \\ \mathbf{I}^c \end{matrix} = \mathbf{V}$$

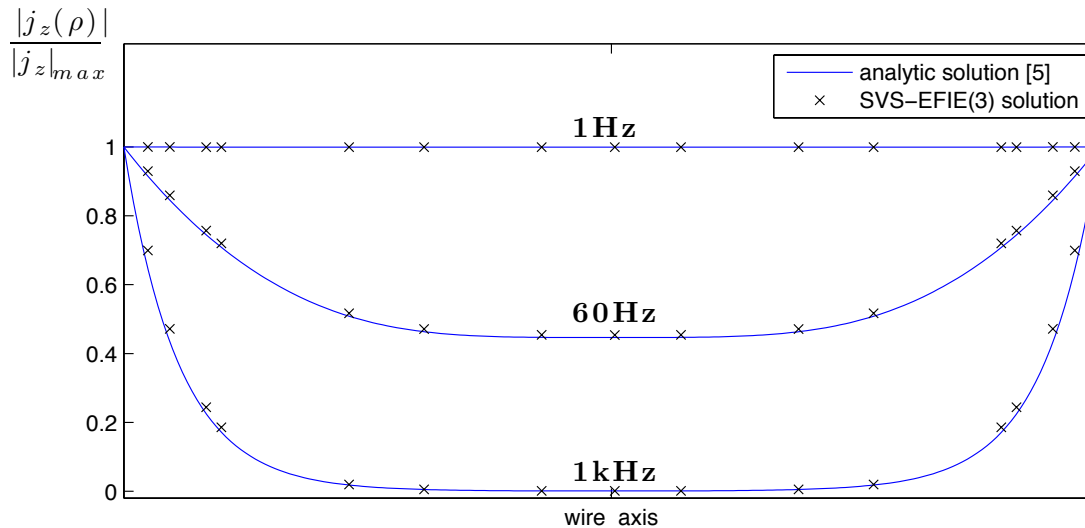
$$\begin{matrix}
 H_0^{(2)}(k_\sigma |\vec{\rho} - \vec{\rho}'|) & \ln(|\vec{\rho} - \vec{\rho}'|) & H_0^{(2)}(k_\sigma |\vec{\rho} - \vec{\rho}'|)
 \end{matrix}$$



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SVS-EFIE vs. analytic solution

Comparison of new model to the analytic solution for ideal circular cross-section



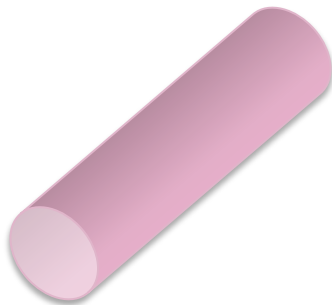
$$\left(\frac{|j_z(\rho)|}{|j_z|_{\max}} \right)_{\text{analytic}} = \frac{J_0(k_\sigma \cdot r)}{J_0(k_\sigma \cdot r_0)}$$

where:

J_0 is Bessel function,

r – radial coordinate

r_0 – radius of cross-section



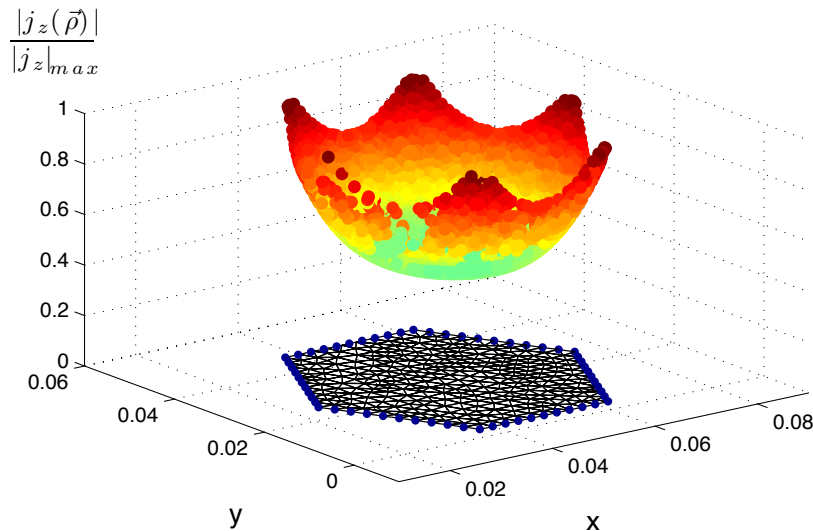
Max Relative error < 2.5%

Simulation Parameters

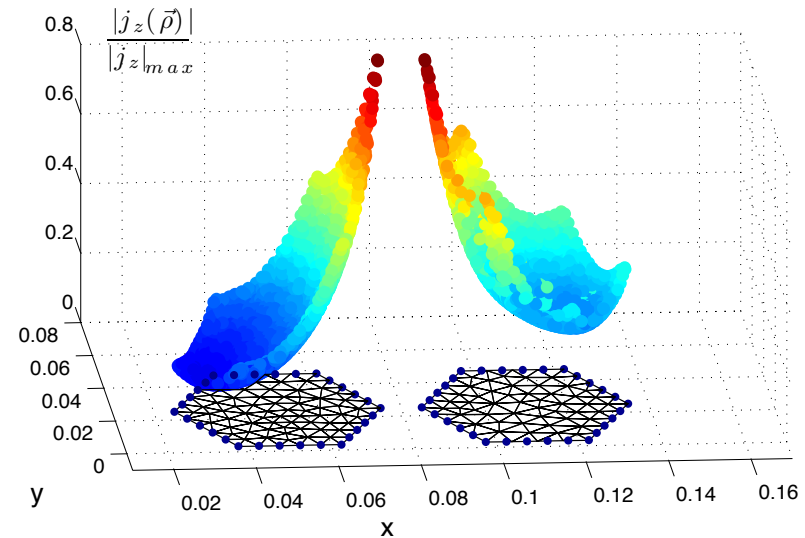
Transmission line	Single aluminum conductor, circular cross-section, $r_0=0.025\text{m}$
Surface mesh	200 linear elements
Volumetric mesh	3,620 triangular elements



SVS-EFIE vs V-EFIE: Example 1



Relative error¹ < 2.7%



Relative error¹ < 1.8%

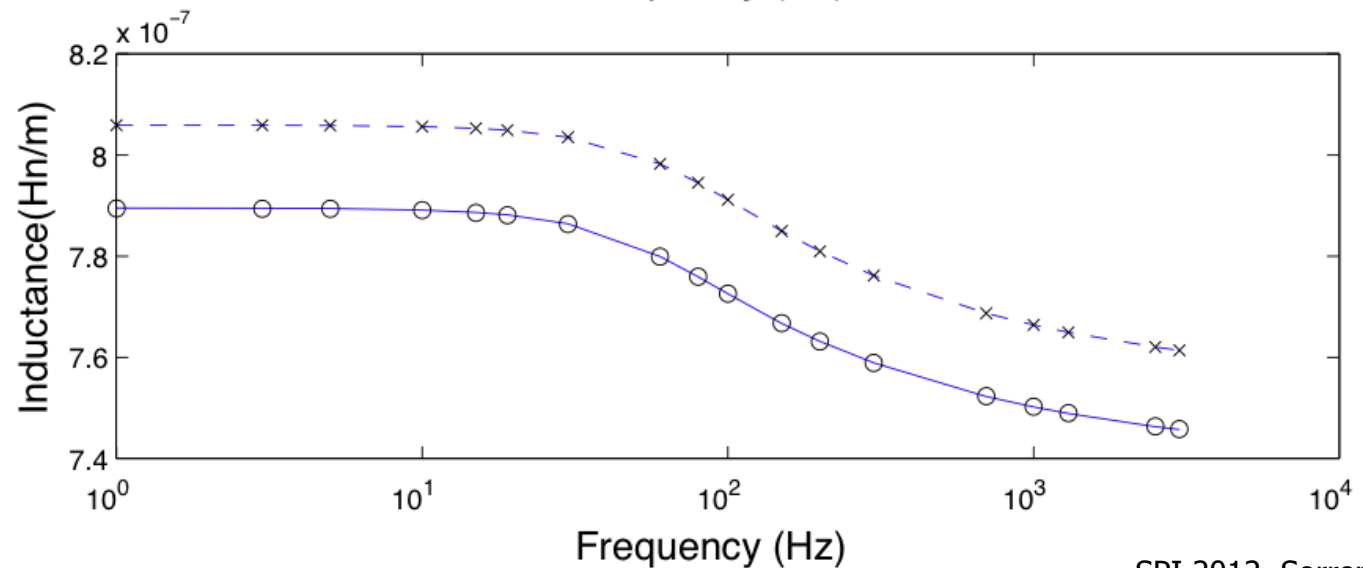
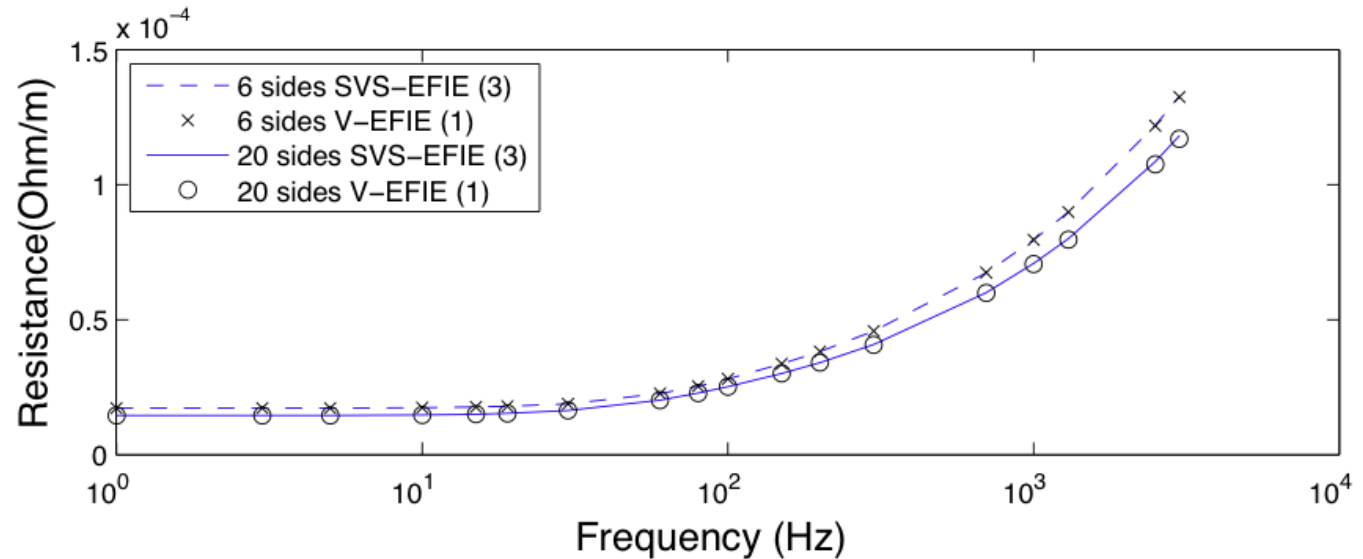
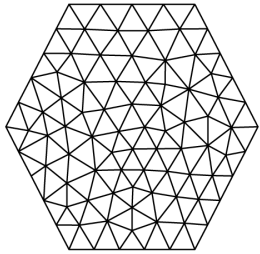
Simulation Parameters

Transmission line	Single aluminum conductor, hexagonal cross-section, $r_0=0.025\text{m}$	2 aluminum conductors of hexagonal cross-section, $r_0=0.025$, centers separated by 0.06m , left – grounded, right – driven 1 V/m
Frequency	60 Hz	60 Hz
Surface mesh	60 linear elements	$2 \times 60 = 120$ linear elements
Volumetric mesh	3,697 triangular elements	3,094 triangular elements

¹ – with respect to traditional Volume-EFIE solution

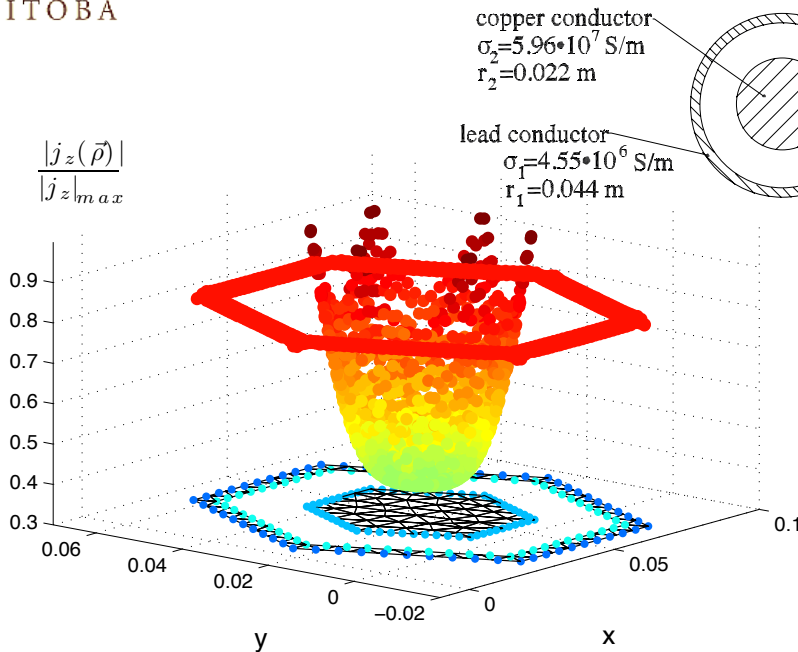


R and L for circular conductor

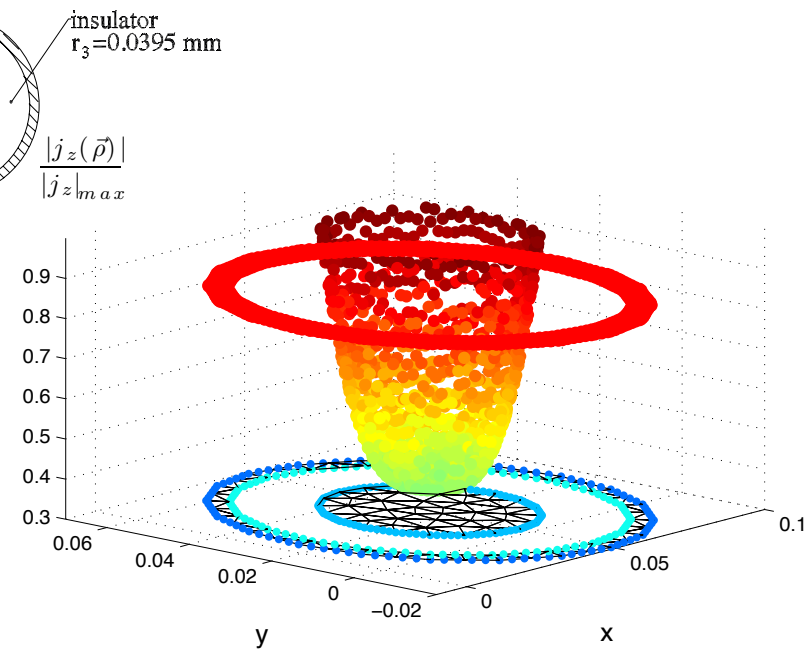




SVS-EFIE vs V-EFIE: Example 2



Relative error¹ < 0.5%



Relative error¹ < 0.5%

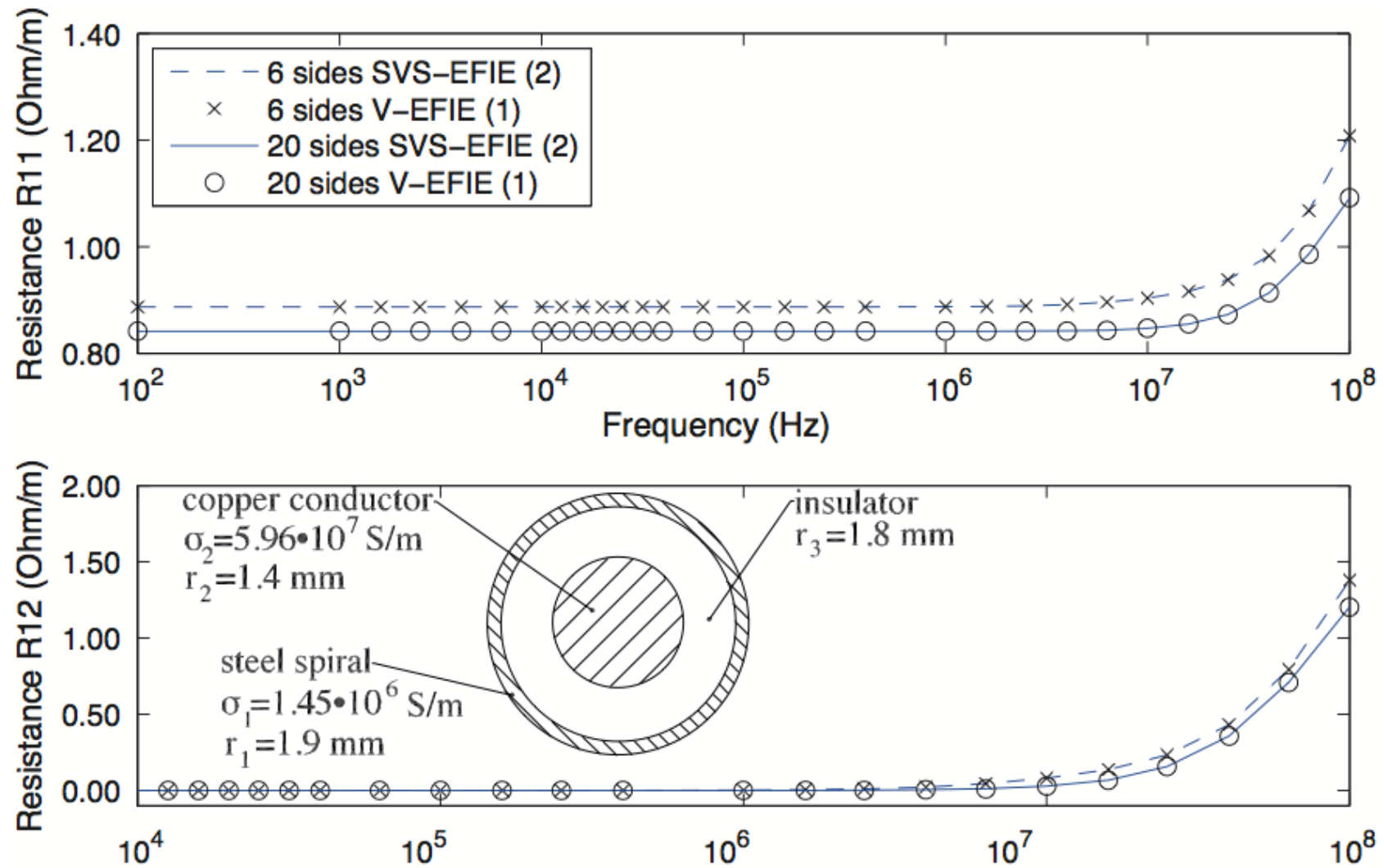
Simulation Parameters

Cross-section approximation	three hexagons	three 20-sided polygons (icosagons)
Mode	60 Hz, inner conductor is grounded, outer is driven 1 V/m	
Surface mesh	3•60=120 linear elements	3•100=3,000 linear elements
Volumetric mesh	1,660 triangular elements	1,376 triangular elements

¹ – with respect to traditional Volume-EFIE solution

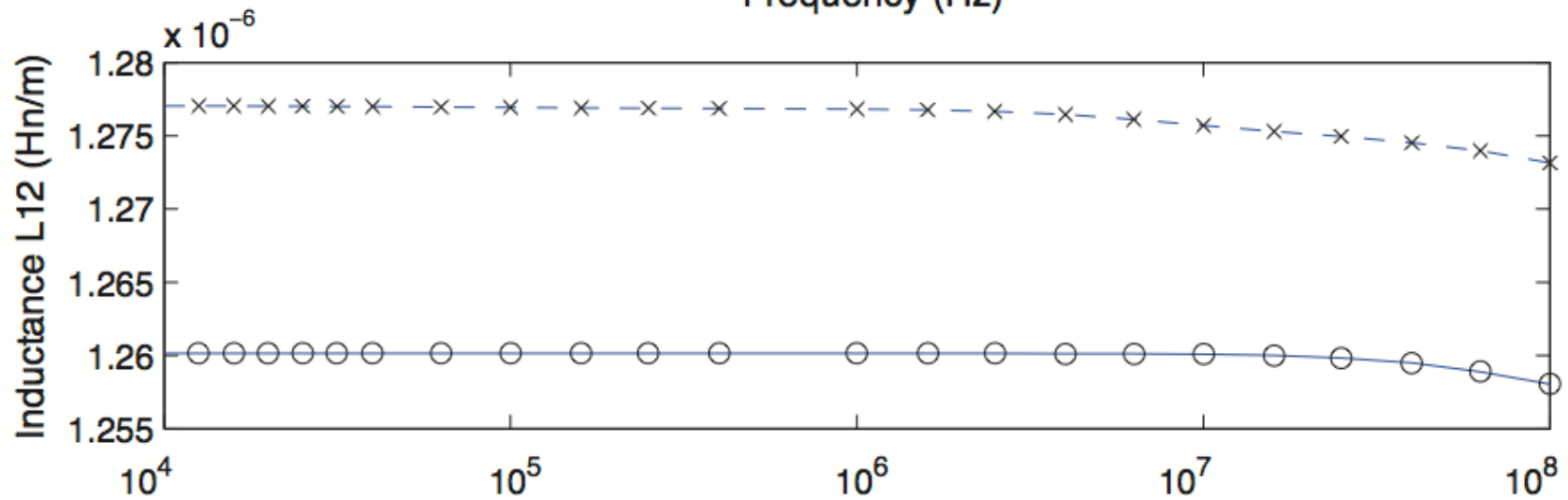
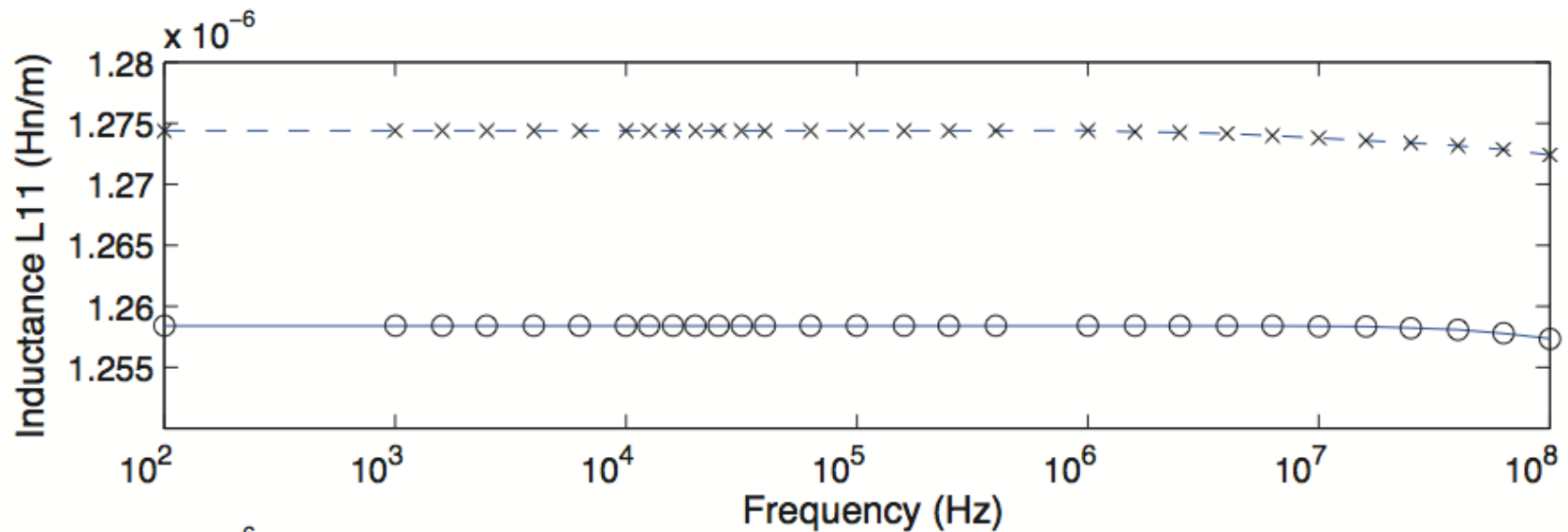


Resistance for coaxial cable





Inductance for coaxial cable





Conclusions

- Surface-Volume-Surface EFIE:
- Pros:
 - Degrees of freedom are surface based
 - Degrees of freedom are independent on frequency
 - Rigorous formulation
 - No loss of accuracy from approximations
 - No derivatives on the Green's function
 - Easily combines with layered media Green's function
 - Highly sparse matrices at high frequencies
- Cons:
 - Requires both surface and volume meshing



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Questions?